One-class logistic regression & friends

Probabilistic anomaly detection as loss minimisation

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Anomaly detection

Identify instances that deviate from some systematic pattern















Anomaly detection

Identify instances that deviate from some systematic pattern















Anomaly detection landscape

Statistical test



One-class SVM



Nearest neighbour



Structural health monitoring



Network analysis



Credit fraud



Anomaly detection landscape





Nearest neighbour

•••

Structural health monitoring



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One-class SVMs: enclosing ball view Find the smallest ball enclosing most of the data



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- imes doesn't focus on probability of instance being anomalous
- imes unclear Bayes-optimal solution









Take-home #1

Anomaly detection = binary classification

• distinguish samples against an implicit background

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Probabilistic anomaly detection = class-probability estimation

• can use familiar tools: logistic regression, boosting, ...

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Surprise

Specific kind of OC-SVM turns out to be a special case!

• gives a different perspective on underlying components

Deconstructing one-class SVMs

Pick an RKHS \mathfrak{H} and desired anomaly fraction $v \in (0,1)$

For data distribution *P*, the OC-SVM solves



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We give a different interpretation for the OC-SVM's components

Density sublevel view of anomaly detection Pick a reference measure μ (e.g., Lebesgue)

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Define anomalies to be instances with low density



Recap: binary classification

Suppose we have positive and negative data distributions P, Q



Recap: binary classification

Suppose we have positive and negative data distributions P, Q

Classify instances based on dominant density



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Anomaly detection as binary classification Consider classification of data distribution *P* versus uniform *Q*



Anomaly detection as binary classification Consider classification of data distribution P versus uniform Q



Anomaly detection = classification against uniform background! (Steinwart & Scovel, 2005)

Fix some density threshold $\alpha > 0$

Anomaly detection seeks a scorer $f \colon \mathfrak{X} \to \mathbb{R}$, where¹

 $f(x) > \alpha \iff p(x) > \alpha$

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(Steinwart & Scovel, 2005): classify data *P* against background *Q*:

$$\min_{f} \mathop{\mathbb{E}}_{P} \left[f(\mathsf{X}) < \alpha \right] + \alpha \cdot \mathop{\mathbb{E}}_{Q} \left[f(\mathsf{X}) > \alpha \right]$$

cost-weighted classification loss

¹ We assume $P(p(X) = \alpha) = 0$

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Anomaly detection as binary classification!

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This talk



• can use familiar tools: logistic regression, boosting, ...

Changing the loss function

What if we instead minimise

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell(+1, f(\mathsf{X})) + \mathop{\mathbb{E}}_{Q} \ell(-1, f(\mathsf{X}))$$

for a generic loss $\ell \colon \{\pm 1\} \times \mathbb{R} \to \mathbb{R}$?

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Result will be exactly per discrimination of *P* versus *Q*

e.g., for proper losses, we recover p(x)

• i.e., we perform density estimation

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 $\ell(-1,f) = \frac{1}{2} \cdot f^2$

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$$= \underset{Q}{\mathbb{E}} \left[-p(\mathsf{X}) \cdot f(\mathsf{X}) + \frac{1}{2} \cdot f(\mathsf{X})^{2} \right]$$

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$$\begin{split} \operatorname{Risk}(f) &= \mathop{\mathbb{E}}_{P} \ell(+1, f(\mathsf{X})) + \mathop{\mathbb{E}}_{Q} \ell(-1, f(\mathsf{X})) \\ &= \mathop{\mathbb{E}}_{P} - f(\mathsf{X}) + \mathop{\mathbb{E}}_{Q} \frac{1}{2} \cdot f(\mathsf{X})^{2} \\ &= \mathop{\mathbb{E}}_{Q} \left[-p(\mathsf{X}) \cdot f(\mathsf{X}) + \frac{1}{2} \cdot f(\mathsf{X})^{2} \right] \\ &= \mathop{\mathbb{E}}_{Q} \left(f(\mathsf{X}) - p(\mathsf{X}) \right)^{2} + \operatorname{constant.} \end{split}$$

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The objective becomes:

$$\operatorname{Risk}(f) = \underset{P}{\mathbb{E}} \ell(+1, f(\mathsf{X})) + \underset{Q}{\mathbb{E}} \ell(-1, f(\mathsf{X}))$$
$$= \underset{P}{\mathbb{E}} - f(\mathsf{X}) + \underset{Q}{\mathbb{E}} \frac{1}{2} \cdot f(\mathsf{X})^{2}$$
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$$= \underset{Q}{\mathbb{E}} \left(f(\mathsf{X}) - p(\mathsf{X}) \right)^{2} + \operatorname{constant.}$$

LSIF loss minimisation = least squares density fitting!

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell(+1, f(\mathsf{X})) + \mathop{\mathbb{E}}_{Q} \ell(-1, f(\mathsf{X}))$$

captures two distinct problem settings

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 $\begin{array}{l} \text{Density sublevel estimation} \\ \ell = \text{cost-sensitive loss} \end{array}$

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captures two distinct problem settings

Density sublevel estimation $\ell = \text{cost-sensitive loss}$

Density estimation $\ell = \text{proper loss}$

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell(+1, f(\mathsf{X})) + \mathop{\mathbb{E}}_{Q} \ell(-1, f(\mathsf{X}))$$

captures two distinct problem settings



What problem lives in between?

Partially proper losses

Partial density estimation

The targets for the two problem settings we've seen are:



The full p(x) for density estimation

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The full p(x) for density estimation and a thresholded version for sublevel estimation

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The full p(x) for density estimation and a thresholded version for sublevel estimation

Natural intermediary: model the tail only

An ensemble of cost-sensitive losses

Density estimation seeks the entire family of sublevel sets



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Each set is attainable with the α cost-sensitive loss

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Each set is attainable with the α cost-sensitive loss

Combine losses for various values of α ?

Consider the cost-sensitive loss

$$\ell_{\mathrm{CS}}(+1,f;c) = (1-c) \cdot \llbracket f < c \rrbracket \qquad \ell_{\mathrm{CS}}(-1,f;c) = c \cdot \llbracket f > c \rrbracket$$

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Every proper loss is a mixture of cost-sensitive losses:

$$\ell(y,f) = \int_0^1 w(c) \cdot \ell_{\mathrm{CS}}(y,f;c) \,\mathrm{d}c.$$

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The weight function w determines modelling effort

Choose a weight which emphasises small c values

For square loss, w(c) = 1, i.e., all costs are equal



Weight functions for proper losses For the LSIF loss, we have smooth $w(c) = (1-c)^{-3}$



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Natural intermediary: weight with partial support

Fix a proper loss ℓ with weight function w

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Suppose for $c_0 \in (0,1)$, we modify the weight to

$$\bar{w}(c) = \llbracket c \le c_0 \rrbracket \cdot w(c)$$

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Effect is to saturate the losses

Consider the cost-sensitive loss with $c_0 = \frac{1}{2}$,

$$\ell(+1,f) = \frac{1}{2} \cdot [\![f < 0]\!] \qquad \ell(-1,f) = \frac{1}{2} \cdot [\![f > 0]\!]$$



Consider the LSIF loss

$$\ell(+1,f) = 1 - f$$
 $\ell(-1,f) = \frac{1}{2} \cdot f^2$



Consider the modified LSIF loss

$$\ell(+1,f) = 1 - (f \wedge 1)$$
 $\ell(-1,f) = \frac{1}{2} \cdot (f \wedge 1)^2$


Partially proper losses

For the LSIF loss, the modified version

$$\bar{\ell}(+1,f) = [\alpha - f]_+$$
 $\bar{\ell}(-1,f) = \frac{1}{2} \cdot (f \wedge \alpha)^2$

is partially proper in the following sense

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Exactly as desired for partial density estimation!

Partially proper losses For the LSIF loss, consider a further modification

$$\tilde{\ell}(+1,f) = [\alpha - f]_+$$
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• only saturate the loss on positives

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Perform capped density estimation

• no longer have full flexibility for high density area

For data distribution P, the OC-SVM solves

$$\min_{f,\alpha} \underbrace{\mathbb{E} \left[\alpha - f(\mathsf{X}) \right]_{+}}_{\text{hinge loss}} + \underbrace{\frac{v}{2} \cdot \|f\|_{\mathcal{H}}^{2}}_{\text{regulariser}} - \underbrace{v \cdot \alpha}_{v-\text{SVM relic}}$$

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while we solve

$$\min_{f} \underbrace{\mathbb{E} \left[\alpha - f(\mathsf{X}) \right]_{+}}_{\mathbf{capped proper loss}} + \underbrace{\mathbb{E} \left[\frac{1}{2} \cdot f(\mathsf{X})^{2} \right]_{\mathcal{Q}}}_{\mathbf{background contrast}}$$

This talk

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Anomaly detection = binary classification

• distinguish samples against an implicit background

Take-home #2

Probabilistic anomaly detection = class-probability estimation

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Kernel absorption

To obtain tail density probabilities, we propose to minimise

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Practically, we may pick f from an RKHS $\mathcal H$ via

$$\min_{f} \mathop{\mathbb{E}}_{P} [\alpha - f(\mathsf{X})]_{+} + \mathop{\mathbb{E}}_{Q} \frac{1}{2} \cdot f(\mathsf{X})^{2} + \frac{\gamma}{2} \cdot ||f||_{\mathcal{H}}^{2}$$

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Convex, but requires computing a high-dimensional integral

A simple trick lets us side-step this

A kernel trick Observe that

$$\mathbb{E} \frac{1}{2} \cdot f(\mathsf{X})^2 + \frac{\gamma}{2} \cdot \|f\|_{\mathcal{H}}^2 = \|f\|_{L_2(\mu)}^2 + \frac{\gamma}{2} \cdot \|f\|_{\mathcal{H}}^2$$

• standard plus Hilbert-space square norm

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Fortuitously, we can write (McCullagh and Møller, 2006) $\|f\|_{L_2(\mu)}^2 + \gamma \cdot \|f\|_{\mathcal{H}}^2 = \|f\|_{\bar{\mathcal{H}}(\gamma,\mu)}^2$

for some modified RKHS $\bar{\mathcal{H}}(\gamma,\mu)$

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This obviates the need for approximating the expectation!

A kernel trick: comments

Connection to point processes is unsurprising

• latter is scaled density estimation (Fithian & Hastie, 2013)

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Penalty $\|f\|^2_{ar{\mathcal{H}}(\gamma,\mu)}$ bakes in measure μ and regulariser

• model complexity plus discrimination

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New kernel \bar{k} may not have analytic form

• can approximate with Nyström method

For data distribution P, the OC-SVM solves



For data distribution P, the OC-SVM solves



while we solve



For data distribution P, the OC-SVM solves



How do we control the threshold α ?

Alarm rate control

Parametrising anomaly level

To obtain tail density probabilities, we propose to minimise

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More intuitive: given $v \in (0,1)$, implicitly use α_v such that

 $P(p(X) < \alpha_v) = v$

- quantile of the random variable p(X)
- v specifies the alarm rate of our predictor

Pinball loss

Recall that the median $lpha_{1/2}$ of a distribution P is

$$\alpha_{1/2} = \operatorname*{argmin}_{\alpha \in \mathbb{R}} \underset{P}{\mathbb{E}} |\mathsf{X} - \alpha|$$

Pinball loss Recall that the median $\alpha_{1/2}$ of a distribution *P* is

$$\alpha_{1/2} = \operatorname*{argmin}_{\alpha \in \mathbb{R}} \underset{P}{\mathbb{E}} |\mathsf{X} - \alpha|$$

More generally, the vth quantile of a distribution P is

$$\alpha_{v} = \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}} \underset{P}{\mathbb{E}} \left[\phi_{\text{pin}}(\mathsf{X} - \alpha; v) \right]$$

for the pinball loss $\phi_{\rm pin}$



The pinball loss is equivalently

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Thus, we have

$$\mathbb{E}_{P}[\alpha - f(\mathsf{X})]_{+} = \mathbb{E}_{P}\left[\phi_{\text{pin}}(f(\mathsf{X}) - \alpha; \mathbf{v})\right] - \mathbf{v} \cdot \mathbb{E}_{P}[f(\mathsf{X})] + \mathbf{v} \cdot \alpha$$

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Thus, we may jointly minimise

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$$\min_{f,\alpha} \mathop{\mathbb{E}}_{P} \left[\alpha - f(\mathsf{X}) \right]_{+} - \mathbf{v} \cdot \alpha + \frac{1}{2} \cdot \|f\|_{\mathcal{H}}^{2}$$

and obtain α^* as the *v*th quantile of $f^*(X)$!

Summary: deconstructing one-class SVMs For data distribution *P*, the OC-SVM solves


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while we solve



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Note this is just one special case of our framework

Empirical illustration

Qualitative results

Augment usps test instances with one-hot encoding of label

Qualitative results

Augment usps test instances with one-hot encoding of label

Identify inliers



Qualitative results

Augment usps test instances with one-hot encoding of label

Identify inliers and outliers



Quantitative results

We fit our model to a "normal" sample on three datasets

- usps: digit o
- sat: largest 3 classes
- art: $\sim mixture \ of \ Gaussians$

Evaluate classification performance on a test sample of normal and anomalous instances

Quantitative results: usps score distribution Scores for digit 0 on train and test set largely agree

Scores for digit 1–9 distinct, despite being unseen at train time



Quantitative results: alarm-miss curves



Summary

This talk

Take-home #1

Anomaly detection = binary classification

• distinguish samples against an implicit background

Take-home #2

Probabilistic anomaly detection = class-probability estimation

• can use familiar tools: logistic regression, boosting, ...



Deconstructing one-class SVMs

Pick an RKHS ${\mathfrak H}$ and desired anomaly fraction ${m v}\in(0,1)$

For data distribution P, the OC-SVM solves



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$$\min_{f,\alpha} \underbrace{\mathbb{E}_{p}[\alpha - f(\mathsf{X})]_{+}}_{\text{hinge-loss}} + \underbrace{\frac{v}{2} \cdot \|f\|_{\mathcal{H}}^{2}}_{\text{regulariser}} - \underbrace{v \cdot \alpha}_{v - \text{SVM-relic}}$$

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Questions nonetheless remain:

- implicit μ, γ for Gaussian kernel?
- avoiding need for density for minimum volume sets?
- Ink interpretation of robust versions of loss?

Thanks!

